On a pathwise stochastic control problem Les Houches, March 2023

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Joint work, with N. Bhauryal (GFMUL) and C. Oliveira (Norwegian Univ. of Sc. and Technology)

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Consider the action functional

$$
S_t[Z] = E \int_t^T \left[\frac{1}{2}|DZ_s|^2 + V(Z_s)\right] ds + S(Z_T)
$$

defined for diffusion processes of the form

$$
dZ_s = \sqrt{\nu} dW_s + DZ_s ds, Z_t = x
$$

where $\nu > 0$, $DZ_s \equiv u(s, Z_s)$, *u* with some regularity, i.e the process is Markov.

If we minimise *S* the value function satisfies the HJB equation

$$
\frac{\partial S}{\partial t} - \frac{1}{2} |\nabla S|^2 + \frac{\nu}{2} \Delta S + V = 0, \quad S(T) = S
$$

and the critical drift $u = -\nabla S$ satisfies a Burgers' eq.

$$
\frac{\partial u}{\partial t} + (u \cdot \nabla)u + \frac{\nu}{2}\Delta u - \nabla V = 0, \quad u(T) = -\nabla S
$$

Well known relation with Optimal transport via Girsanov's theorem:

since the law of *Z* (*Q*) is abs. continuous w.r.t the law of the Brownian motion (with coeff. $\sqrt{\nu}$) *R* with Radon-Nikodym derivative

$$
\exp\left(\sqrt{\nu}\int_t^T u(Z_s)dW_s-\frac{\nu}{2}\int_t^T|u(Z_s)|^2ds\right)
$$

in the optimal control problem above we are looking at the relative entropy

$$
H(Q|R) = E^Q\Big(\log \frac{dQ}{dR}\Big) \simeq S
$$

Here we consider a pathwise version of this problem.

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Define the random action functional

$$
S_{t,x}(Z,u) = \int_t^T \left(L(u(s,Z_s)) + V(Z_s) \right) ds + S(Z_T),
$$

\n
$$
dZ_s = \sqrt{\nu} dW_s + u(s,Z_s) ds, \quad Z_t = x \text{ and } 0 \le t \le s \le T
$$

(*u* random) and the value process

$$
U_t(x) = \text{ess inf}_{u \in \mathcal{U}} S_{t,x}(Z, u).
$$

To guarantee that there is a strong solution to *Z* for each drift *u*, we define U as the set of all processes (not necessarily adapted) which are uniformly bounded and s.t

$$
|u(t, x, \omega) - u(t', x', \omega')| \leq C(|t - t'| + |x - x'| + |\omega - \omega'|)
$$
 for some $C > 0$.

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For every stochastic process *h* with time derivative in *L* ² and such that $h(t) = 0$ (here $L(u) = \frac{1}{2}|u|^2$)

$$
\left. \frac{d}{d\varepsilon} \right|_{\varepsilon=0} S(Z+\varepsilon h) = \int_t^T (u_s(Z_s).\dot{h}(s)) ds + \int_t^T \nabla V(Z_s).\dot{h}(s) dt + \nabla S(Z_T).\dot{h}(T)
$$

$$
d\Big(u_s(Z_s).h(s)\Big)=d\big(u_s(Z_s)\Big).h(s)+u_s(Z_s).h(s)ds,
$$

and since $h(t) = 0$ we have, for all h ,

$$
\frac{d}{d\varepsilon}\bigg|_{\varepsilon=0} S(Z+\varepsilon h) = \int_t^T h(t) \cdot \left[-du_s(Z_s) + \nabla V(Z_s)\right] ds
$$

$$
+ \left[\nabla S(Z_T) - u_T(Z_T)\right] h(T)
$$

So

$$
d(u_s(Z_s)) = \nabla V(Z_s) ds, \quad u_T(Z_T) = \nabla S(Z_T)
$$

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We cannot expect *u* to be adapted in general.

Example: $L(u) = \frac{1}{2} |u|^2$ and $V \equiv 0$. Then $u(s, Z_s) = \nabla S(Z_T)$ for $t \leq s \leq T$, and

$$
Z(s) = x + \int_t^s \nabla S(Z_T) d\tau + \int_t^s \sqrt{\nu} dW(\tau).
$$

So *Z* is not adapted to an increasing filtration up to time *s*. We shall use non-adapted stochastic calculus.

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Consider:

Prob. space: $\Omega = {\omega \in C([t, T]; \mathbb{R}^n)}, \omega(t) = x, \omega \text{ continuous}}$, P Wiener measure (law of Brownian motion)

Cameron-Martin (tangent) space:

 $H = \{h : [t, T] \rightarrow \mathbb{R}^n : h(t) = 0, h \text{ is a.c. and } \int_t^T |\frac{d}{ds}h(s)|^2 ds < +\infty\}.$

If *F* is a random variable in Ω, define

$$
D_h F(\omega) = \lim_{\varepsilon \to 0} \frac{1}{\varepsilon} [F(\omega + \epsilon h) - F(w)]
$$

Since *H* is a Hilbert space, the derivative gives rise to a gradient operator, $\langle \nabla F, h \rangle_H = D_h F$.

Defining

$$
D_{\rm s}F(\omega)=\frac{d}{d{\rm s}}\nabla F(\omega),
$$

we have $D_h F = \int_t^T D_s F \frac{d}{ds} h(s) ds$.

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The Itô (-Skorohod) integral of non necessarily adapted processes, $\int u \ dW$, is the L^p limit, when it exists, of sums

$$
\sum_{k} \mathcal{M}_{k}(u)(W(s_{k+1})-W(s_{k})) - \frac{1}{s_{k+1}-s_{k}} \int_{s_{k}}^{s_{k+1}} \int_{s_{k}}^{s_{k+1}} D_{s} u_{\tau} d s d\tau
$$

where

$$
\mathcal{M}_k(u)=\frac{1}{s_{k+1}-s_k}\int_{s_k}^{s_{k+1}}u_{\tau}d\tau,
$$

The Stratonovich (-Skorohod) integral *∫ u* ∘ *dW* is the limit of sums

$$
\sum_{k} \mathcal{M}_k(u) (W(s_{k+1}) - W(s_k))
$$

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Relation between the two integrals:

$$
\int_t^T u_s \circ dW_s = \int_t^T u_s dW_s + \frac{1}{2} \int_t^T (\mathbb{D}u)_s ds,
$$

 $(D\cup\cup)_{\mathcal{S}} = D_{\mathcal{S}}^+\cup_{\mathcal{S}} + D_{\mathcal{S}}^-\cup_{\mathcal{S}}$, with $D_s^+ u_s = \lim_{\tau \to s^+} D_s u_\tau, \ D_s^- u_s = \lim_{\tau \to s^-} D_s u_\tau$

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As in the adapted case, Stratonovich integration obeys the rules of ordinary differential calculus.

Itô-Wentzell formula in the non-adapted case (Stratonovich version) by Ocone and Pardoux.

If
$$
Z_s = Z_t + \int_t^s B_\tau \circ dW_\tau + \int_t^s A_\tau d\tau
$$
 and
\n $F_s(x) = F_t(x) + \int_t^s H_\tau(x) \circ dW_\tau + \int_t^s G_\tau(x) d\tau$,
\n $F_s(Z_s) = F_t(Z_t) + \sum_k \int_t^s \nabla F_\tau(Z_\tau) \cdot B_\tau^k \circ dW_\tau^k + \int_t^s \nabla F_\tau(Z_\tau) \cdot A_\tau d\tau$
\n $+ \int_t^s H_\tau(Z_\tau) \circ dW_\tau + \int_t^s G_\tau(Z_\tau) d\tau$

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[Main result](#page-11-0)

Theorem. The value process U is continuous in $\mathbb{R}^n \times [t, T]$, Lipchitz in space uniformly in *t* and α -Hölder in *t* uniformly in *x* for $\alpha < \frac{1}{2}$. It is a viscosity solution of the terminal value problem (stochastic HJB equation with transport noise)

$$
\begin{cases}\ndv(s,x) = -\sqrt{\nu}\nabla v(s,x) \circ dW(s) \\
\qquad + \left(V(x) + \text{ess inf}_u(L(u) + u \cdot \nabla v)\right) \text{d}s, \\
v(T,x) = S(x)\n\end{cases}
$$

or, in Itô(-Skorohod) form,

$$
\begin{cases}\ndv(s,x) = -\sqrt{\nu}\nabla v(s,x).dW(s) \\
+ \left(V(x) + \text{ess inf}_{u}\left(L(u) + u \cdot \nabla v\right) + \frac{\sqrt{\nu}}{2} \mathbb{D}_{s}(\nabla v)(s,x)\right) ds, \\
v(T,x) = S(x).\n\end{cases}
$$

Moreover the solution is unique.

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Viscosity solutions: (sub + super)

Let Φ be the solution of $d\Phi = -\sqrt{\nu}\nabla \Phi \circ dW_s$, $\Phi(T, x) = S(x)$, $F(x, v) = V(x) + \text{ess inf}_{u}(L(u) + u \cdot \nabla v).$

An upper (resp. lower) semi-continuous function *v* defined on $[0, T] \times \mathbb{R}^n$ is a viscosity sub-solution (resp. super-solution) if it is bounded from above (resp. from below) with terminal data satisfying $v(\cdot, T) \leq S(x)$ (resp. $v(\cdot, T) \geq S(x)$), and, whenever $\phi \in C_b^2(\mathbb{R}^n)$, $\delta=\delta(\phi)>0,\, g\in C^1([0,\,T]),$ $\Phi(\textbf{\textit{s}},x)\in C^2_b(\mathbb R^n),$ for $\textbf{\textit{s}}\in(s_0-\delta,s_0+\delta),$ and the map $(s, x) \mapsto v(s, x) - \Phi(s, x) - g(s)$ attains a local maximum (resp. local minimum) at $(s_0, x_0) \in \mathbb{R}^n \times (s_0 - \delta, s_0 + \delta)$, then

 $-g'(s_0) \le F(\nabla \Phi(s_0, x_0), x_0)$ (resp. $-g'(s_0) \ge F(\nabla \Phi(s_0, x_0), x_0)$).

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It follows from Bellman's optimality principle:

$$
U_t(x) = \text{ess inf}_u \left\{ \int_t^{t+\delta} (L(u) + V(Z_s)) ds \right\} + U_{t+\delta}(Z_{t+\delta})
$$

and uniqueness from a comparison principle:

If *u* and *v* are a viscosity solution sub-solution and a super-solution respectively, then

$$
\sup_{x \in B_R(0)} (u(x,s) - v(x,s))_+ = \sup_{x \in B_R(0)} (u(x,0) - v(x,0))_+
$$

for all $s \in [0, T]$ and $\forall R > 0$.

The case $L(u) = \frac{1}{2} |u|^2$. The equation for the drift,

$$
\begin{cases}\n d u(s,x) = -\sqrt{\nu} \nabla u(s,x) \circ dW(s) \\
 -[(u \cdot \nabla u)(s,x) - \nabla V(x)] \, ds, \\
 u(T,x) = \nabla S(x)\n\end{cases}
$$

We can reverse time, defining $\tilde{u}(s, x) = u(T - t, x)$ and

$$
\begin{cases}\n d\tilde{u}(s,x) = -\sqrt{\nu}\nabla \tilde{u}(s,x) \circ dW(s) \\
 \quad + [(\tilde{u} \cdot \nabla \tilde{u})(s,x) - \nabla V(x)]\mathrm{d}s, \\
 \tilde{u}(t,x) = \nabla S(x)\n\end{cases}
$$

(a forward problem).

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Symmetries of the action (again for $L(u) = \frac{1}{2}|u|^2$):

Consider a smooth (possibly random) vector field *Y* : $]t, T[\times \mathbb{R}^n \to [t, T] \times \mathbb{R}^n$ of the form $Y(s, x) = (T(s), X(s, x))$. Denote by $\Phi_{\epsilon} = (\varphi_{\epsilon}^0, \varphi_{\epsilon})$ the flow generated by Y:

$$
\left.\frac{d}{d\epsilon}\right|_{\epsilon=0}\varphi^0_\epsilon(t)=\left.\mathcal{T}(t),\quad \left.\frac{d}{d\epsilon}\right|_{\epsilon=0}\varphi_\epsilon(t,x)=X(t,x).
$$

A vector field *Y* as above is a Lagrangian infinitesimal variation symmetry of the action functional *S* if its flow is conserved, i.e, $\forall t_1, t_2 \in [t, T]$, $t_1 < t_2$ and every $\epsilon > 0$, we have, a.s.,

$$
\int_{t_1}^{t_2}\Big(\frac{1}{2}|D(Z_s)|^2+V(Z_s)\Big){\rm d} s=\int_{\varphi_\varepsilon^0(t_1)}^{\varphi_\varepsilon^0(t_2)}\Big(\frac{1}{2}|D(\varphi_\varepsilon(Z_{(\varphi_\varepsilon^0)^{-1}(s)}))|^2\\+V(\varphi_\varepsilon(Z_{(\varphi_\varepsilon^0)^{-1}(s)})){\rm d} s.
$$

On the critical drift we have

$$
D\left(\langle X, u\rangle -T\left(\frac{1}{2}|u|^2-V\right)\right)(s,Z_s)=\frac{\nu}{2}T(s)\Delta V(Z_s).
$$

譶 N. Bhauryal, A.B.C. and C. Oliveira, *Pathwise stochastic control and a class of stochastic partial differential equations*, https://arxiv.org/pdf/2301.09214.pdf