Optimal transport problems in microstructure modelling

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Collaborators

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- Steve Roper: University of Glasgow
- Mason Pearce: PhD student, Heriot-Watt University
- Piet Kok: Tata Steel R&D (retired) & Ghent University
- Wil Spanjer: Tata Steel R&D (retired)
- Karo Sedighiani: Tata Steel R&D

Today's talk

How optimal transport theory can be used to generate geometric models of the microstructure of steels, foams, concrete, ...



Part I: Background in steel

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Atoms in metals form lattices.





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- Zoom out: Metals are composed of grains.





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- Zoom out: Metals are composed of grains.





 Grains often resemble polyhedra. Under idealised cooling conditions, grains would form a Voronoi diagram.

• High-performance steels: Grains of different sizes & shapes.



Figure: Left: DC06 steel grade. Right: Dual phase steel.

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- Grain geometry affects the mechanical properties of steel.
- Goal of Tata Steel: Improve steel grades (alloys) and steel-forming processes by controlling the size and geometry of the grains.

Multiscale microstructure modelling

Approach: Computational homogenisation

- Geometric modelling: Generate a geometric model (Voronoi tessellation or Laguerre tessellation) of the steel microstructure.
- Computational plasticity: Assign mechanical propertes to each grain. Simulate standard mechanical tests (uni-axial load, shear).



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Part II: Background in semi-discrete OT

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Laguerre tessellations

The Laguerre tessellation of $\Omega \subset \mathbb{R}^d$ generated by the weighted points $\{(x_i, w_i)\}_{i=1}^n, x_i \in \Omega, w_i \in \mathbb{R}$, is the partition $\{L_i\}_{i=1}^n$ of Ω defined by

$$L_i = \{ x \in \Omega : |x - x_i|^2 - w_i \le |x - x_j|^2 - w_j \ \forall j \}.$$



Laguerre cells are convex polygons in 2D and polyhedra in 3D.

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$$W_2^2\Big(\mathcal{L}^d \sqcup \Omega, \sum_i v_i \delta_{x_i}\Big) = \min_{\substack{\text{partitions } \{U_i\} \text{ of } \Omega \\ \mathcal{L}^d(U_i) = v_i \ \forall \ i}} \sum_i \int_{U_i} |x - x_i|^2 \, dx$$

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The optimal partition is a Laguerre tessellation $\{L_i\}$ with cells of volume $\{v_i\}$

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Part III: Main results

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Bourne, Kok, Roper & Spanjer (2020), Bourne, Pearce & Roper (2023)

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• Very fast algorithms (damped Newton method) and software:

Kitagawa, Mérigot & Thibert (2019), A. Gallouët, Mérigot & Thibert (2022), Lévy, Mohayaee & von Hausegger (2021), Lévy (2015), Mérigot (2011), ... pysdot (Mérigot & Leclerc), Geogram (Lévy), sdot (Meyron), MATLAB-SDOT

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- Choice of x_1, \ldots, x_n gives some control over the spatial distribution.
- Generate 'regular' microstructures by solving a quantization problem:

$$\min_{\{x_1,\dots,x_n\}} W_2\left(1,\sum_{i=1}^n v_i\delta_{x_i}\right)$$

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Algorithms/convergence: Mérigot, Santambrogio & Sarrazin (2021), B., Kok, Roper & Spanjer (2020), Xin, Lévy et al. (2016), Mérigot & Mirebeau (2016)

Example

Dual phase microstructure: 30 grains area a, 10 grains area 10a



Figure: Left: *x_i* drawn at random. Right: Locally-optimal quantizer.

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$$\min_{\{x_1,\dots,x_n\}} E(x_1,\dots,x_n), \qquad E(x_1,\dots,x_n) = W_2\Big(1,\sum_{i=1}^n v_i \delta_{x_i}\Big)$$

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• Critical points of E: Centroidal Laguerre tessellations

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- Critical points of E: Centroidal Laguerre tessellations
- Generalised Lloyd's algorithm. Iteration k:

- $\{L_i^{(k)}\}$ = optimal partition for OT problem $W_2\left(1, \sum_{i=1}^n v_i \delta_{x_i^{(k)}}\right)$

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- Convergence: Mérigot, Santambrogio & Sarrazin (2021), Bourne, Kok, Roper & Spanjer (2020)
- Non-convexity: Non-convexity is our friend!

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i=1

Using non-convexity to control spatial distribution

Initial choice of seeds $x_i^{(0)}$ has a big effect on the pattern:







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Optimal transport with periodic quadratic cost

Same method works for periodic Laguerre tessellations (important for computational homogenisation), where

$$L_i^{\text{per}} = \{ x \in \Omega : |x - x_i|_{\text{per}}^2 - w_i \le |x - x_j|_{\text{per}}^2 - w_j \ \forall j \}.$$



Bourne, Pearce & Roper (2023)

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Fitting volumes and centroids

Question: Given a list of target volumes v_1, \ldots, v_n and target centroids c_1, \ldots, c_n , find a Laguerre tessellation $\{L_i\}_{i=1}^n$ with grains of correct volume and 'minimum centroid error'.

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Notation: The centroid (barycentre) of a grain L_i is

$$b(L_i) = \frac{1}{\mathcal{L}^d(L_i)} \int_{L_i} x \, \mathrm{d}x.$$

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Theorem (B., Pearce, Roper)

Given a list of target volumes v_1, \ldots, v_n and target centroids c_1, \ldots, c_n , suppose there exists a Laguerre tessellation $\{L_i(X^*, w^*)\}_{i=1}^n$ such that $\mathcal{L}^d(L_i) = v_i$ and $b(L_i) = c_i$ for all *i*. Then

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1. The Laguerre diagram is unique.

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(The *grains* are unique. The seeds can be uniformly translated and dilated, $x'_i = \lambda x_i + t$ for all *i*, without changing the grains L_i .)

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- 1. The Laguerre diagram is unique.
- 2. The seeds $X^* = (x_1^*, \dots, x_n^*)$ maximise the concave function $H : (\mathbb{R}^d)^n \to \mathbb{R}$,

$$H(X) = \frac{1}{2}W_2^2 \left(1, \sum_{i=1}^n v_i \delta_{x_i}\right) + \sum_{i=1}^n v_i c_i \cdot x_i - \frac{1}{2}\sum_{i=1}^n v_i |x_i|^2.$$

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H is C^1 on the set $\{(x_1, \ldots, x_n) \in (\mathbb{R}^d)^n : x_i \neq x_j \ \forall i \neq j\}$ and

$$\frac{\partial H}{\partial x_i} = v_i(c_i - b(L_i)).$$

(Mérigot, Santambrogio & Sarrazin (2021))

Preliminary results: General case

Given a list of target volumes v_1, \ldots, v_n and target centroids c_1, \ldots, c_n , find a Laguerre tessellation $\{L_i\}_{i=1}^n$ such that $\mathcal{L}^d(L_i) = v_i$ for all i and $\sum_i |v_i(b(L_i) - c_i)|^2$ is minimal.



Left: EBSD image. Right: Fitted diagram. The blue dots are the target centroids, the red dots are the actual centroids.

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We can represent anisotropic microstructures by anisotropic Laguerre diagrams.



A. Alpers, A. Brieden, P. Gritzmann, A. Lyckegaard, and H.F. Poulsen. Generalized balanced power diagrams for 3D representations of polycrystals. *Philos. Mag.* 95(9): 1016-1028, 2015.

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The anisotropic Laguerre tessellation generated by the weighted points $\{(x_i, w_i, A_i)\}_{i=1}^n$, where $x_i \in \Omega$, $w_i \in \mathbb{R}$, A_i are SPD matrices, is the partition $\{L_i\}_{i=1}^n$ of Ω defined by

$$L_{i} = \left\{ x \in \Omega : |x - x_{i}|_{A_{i}}^{2} - w_{i} \le |x - x_{j}|_{A_{j}}^{2} - w_{j} \forall j \right\}$$

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where $|\cdot|_A$ is the A-norm: $|x - x_i|_A^2 = (x - x_i) \cdot A(x - x_i)$.

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The A_i matrices give some control over the aspect ratio of the cells.

Q. Can we choose the generators $(x_1, w_1, A_1), \ldots, (x_n, w_n, A_n)$ so that the anisotropic Laguerre cells have desired volumes v_1, \ldots, v_n ?

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• For any $\{x_i\}$, $\{A_i\}$, solve the semi-discrete transport problem

$$W_c\left(1,\sum_{i=1}^n v_i\delta_{x_i}\right)$$

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with anisotropic cost $c(x, x_i) = |x - x_i|_{A_i}^2$.

The optimal partition {L_i}ⁿ_{i=1} is an anisotropic Laguerre tessellation and L^d(L_i) = v_i ∀ i.

Q. Can we choose the generators $(x_1, w_1, A_1), \ldots, (x_n, w_n, A_n)$ so that the anisotropic Laguerre cells have desired volumes v_1, \ldots, v_n ?

A. Yes. Solution(s) using optimal transport theory:

• For any {x_i}, {A_i}, solve the semi-discrete transport problem

$$W_c\left(1,\sum_{i=1}^n v_i\delta_{x_i}\right)$$

with anisotropic cost $c(x, x_i) = |x - x_i|_{A_i}^2$.

- The optimal partition {L_i}ⁿ_{i=1} is an anisotropic Laguerre tessellation and L^d(L_i) = v_i ∀ i.
- Implementation: Maximise the concave function $\mathcal{K}: \mathbb{R}^n \to \mathbb{R}$,

$$\mathcal{K}(w) = \sum_{i=1}^{n} \int_{L_i(w)} (|x - x_i|_{A_i}^2 - w_i) \, \mathrm{d}x + \sum_{i=1}^{n} v_i w_i$$

where

$$L_i(w) = \{ x \in \Omega \ : \ |x - x_i|_{A_i}^2 - w_i \le |x - x_j|_{A_j}^2 - w_j \ \forall j \}.$$

Example

Dual phase microstructure: 100 cells: 70 small cells of area a, 30 large cells of area 10a (error less than 1%). The large cells have two different A_i (15 of each type):



Fitting anisotropic diagrams to EBSD data

Basic fitting: Take x_i , A_i , v_i from EBSD data (grain centroids, ellipsoids, volumes) - solve the semi-discrete OT problem for w_i .



Left: EBSD image from Tata Steel.

Right: Anisotropic Laguerre.

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Implementation issues

Question: How can we compute anisotropic diagrams efficiently?

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- Pixel method. Compute the "anisotropic distance" $(p_i x_j) \cdot A_j(p_i x_j) w_j$ between every pixel *i* and seed *j*.
- Geometric lifting method. Compute a standard power diagram in dimension d + d(d+1)/2, intersect with a surface, project. Boissonnat, Wormser & Yvinec (2007)
- Entropic semi-discrete optimal transport.
- Stochastic optimisation. Genevay, Cuturi, Peyré & Bach (2016)

• Boundary method. Dieci & Walsh III (2019)