# On the existence of Monge maps for the Gromov–Wasserstein problem

Joint work with T. DUMONT (Mines Paristech/MVA), T. LACOMBE (LIGM).

François-Xavier  $\rm VIALARD$  (LIGM - Univ. Gustave Eiffel) March 14th, 2023

École de physique des Houches

# 1. Introduction

How to align clouds of points from different spaces?

- 1. Given a large population of cells.
- 2. Two or more experiences in which cells are killed (you cannot reuse it).
- 3. Observe results: collections of points in  $\mathbb{R}^{d_1}, \mathbb{R}^{d_2}$ .



Figure 1: "Gromov-Wasserstein optimal transport to align single-cell multi-omics data", (Demetci et al.)

#### **Comparing metric-measure spaces**

Let  $\mathcal{X} = \{(X, d, \mu), (X, d) \text{ polish space}, \mu \text{ probability measure}\}.$ How to compare such spaces ? Isometric mm-spaces:  $\varphi : X \mapsto Y$ ,  $\varphi_*(\mu) = \nu$  and  $\varphi$  isometric:  $\varphi^* d_Y = d_X$ .

- Memoli's proposal: quadratic optimization problem.
- Sturm's proposal: finding a common embedding in a metric space.

## Two different distances

 $D^2$  distance: infimum on the set of embeddings, Sturm, 2006

 $D^2(X,Y) := \inf_{\psi,\varphi} \{\inf_{\pi} \langle \pi, d_Z^2(\psi(x),\varphi(y)) \rangle \, ; \, (\psi,\varphi) : (X,Y) \mapsto Z \text{ and } \pi \in C_{\mu_X,\mu_Y} \} \, ,$ 

- $\psi, \varphi$  being isometric embeddings.
- 1. Reformulation on minimising a coupling pseudo-metric on  $X \times Y$ .
- 2. Non-convex optimization problem.



## Two different distances

 $\mathsf{GW}^2$  distance (Memoli): comparison of pairwise distances (distortion distances)

$$\mathsf{GW}^2(X,Y) := \inf_{\pi} \{ \langle \pi(x,y) \otimes \pi(x',y'), | d_X(x,x') - d_Y(y,y') |^2 \rangle \, ; \, \pi \in C_{\mu_X,\mu_Y} \} \, .$$

- 1. Non-convex optimization problem.
- 2. Entropic regularization applies directly.



- 1. Same topology (on compact spaces with uniformly bounded diameters).
- 2. D gives complete metric space, not GW.
- 3. Both are length spaces. E.g.  $(X \times Y, (td_Y^2 + (1-t)d_X^2)^{1/2}, \pi)$  for GW.
- 4. GW has non-negative Alexandrov curvature.

Two contributions on the Gromov-Wasserstein problem.

- 1. (First part) A mathematical study of the structure of the optimizers.
- (Second part) A generalization relevant in practice to an unbalanced setting (e.g. the two point clouds do not have the same total mass).

What are the tools for that?

GW is a quadratic optimization problem on probability measures. Its linearization belongs to optimal transport.

- 1. Known and new technics in optimal transport.
- 2. Extension of part of my work on unbalanced optimal transport.

1. Introduction

1.1. Map solutions of OT

#### Brenier's theorem [?]

Let  $\mu, \nu \in \mathcal{P}(\mathbb{R}^n)$  and  $c(x, y) = |x - y|^2$ . If  $\mu \ll \mathcal{L}^n$ , then there exists a unique solution to ?? induced by a map  $T = \nabla f$ , with f convex.

- Recall that linear optimization (whatever the cost) over the simplex permutation.
- Interest: structure on the minimizers.
- generalized for Riemannian manifolds  ${\mathcal X}$  and  ${\mathcal Y}$  and for other cost functions c.

Twist condition Gangbo's PhD, [?, ?]

We say that c satisfies the twist condition if

for all 
$$x_0 \in \mathcal{X}$$
,  $y \mapsto \nabla_x c(x_0, y) \in T_{x_0} \mathcal{X}$  is injective. (Twist)

Suppose that *c* satisfies (Twist) and assume that any *c*-concave function is differentiable  $\mu$ -a.e. on its domain (e.g.  $\mu \ll \mathcal{L}^n$ ). If  $\mu$  and  $\nu$  have finite transport cost, *then* ?? admits a *unique optimal transport plan*  $\pi^*$  *induced by a* map which is the gradient of a *c*-convex function  $f : \mathcal{X} \to \mathbb{R}$ :

$$\pi^{\star} = (\mathsf{id}, c\operatorname{-} \exp_{\times}(\nabla f))_{\#}\mu.$$

•  $c - \exp_x(p)$  is the unique y such that  $\nabla_x c(x, y) + p = 0$ :

$$c\operatorname{-exp}_{x}(p) = (\nabla_{x}c)^{-1}(x,-p).$$

• usual Riemannian exp when  $c(x, y) = d(x, y)^2/2$ 



Twist condition Gangbo's PhD, [?, ?]

We say that c satisfies the twist condition if

$$\text{for all } x_0 \in \mathcal{X}, \quad y \mapsto \nabla_x c(x_0, y) \in \mathcal{T}_{x_0} \mathcal{X} \text{ is injective.} \tag{Twist}$$

Suppose that *c* satisfies (Twist) and assume that any *c*-concave function is differentiable  $\mu$ -a.e. on its domain (e.g.  $\mu \ll \mathcal{L}^n$ ). If  $\mu$  and  $\nu$  have finite transport cost, *then* ?? admits a *unique optimal transport plan*  $\pi^*$  *induced by a* map which is the gradient of a *c*-convex function  $f : \mathcal{X} \to \mathbb{R}$ :

$$\pi^{\star} = (\mathsf{id}, c\operatorname{-} \exp_{\mathsf{x}}(\nabla f))_{\#}\mu.$$

- examples: twist  $\begin{array}{c|c} |x - y|^2 & \text{in } \mathbb{R}^n & \checkmark \\ \langle x, y \rangle & \text{in } \mathbb{R}^n & \checkmark \\ \langle x, y \rangle & \text{on } \mathbb{S}^{n-1} & \cdot \end{array}$
- other formulation:

 $\forall y_1 \neq y_2, x \mapsto c(x, y_1) - c(x, y_2)$  has no critical point.



#### Subtwist condition [?, ?]

We say that c satisfies the subtwist condition if

 $\forall y_1 \neq y_2, x \mapsto c(x, y_1) - c(x, y_2)$  has at most 2 critical points. (Subtwist)

Suppose that *c* satisfies (Subtwist). Under the same assumptions than before, **??** admits a unique optimal transport plan  $\pi^*$  induced by the **union of a map** and an anti-map:

$$\pi^{\star} = (\mathsf{id}, G)_{\#}\bar{\mu} + (H, \mathsf{id})_{\#}(\nu - G_{\#}\bar{\mu})$$

for  $G : \mathcal{X} \to \mathcal{Y}$ ,  $H : \mathcal{Y} \to \mathcal{X}$  and  $0 \leq \overline{\mu} \leq \mu$  s.t.  $\nu - G_{\#}\overline{\mu}$  vanishes on the range of G.

		twist	subtwist
$\langle x, y \rangle$	on $\mathbb{S}^{n-1}$	•	$\checkmark$



m-twist condition [?]

We say that c satisfies a m-twist condition if

$$\forall x_0 \in \mathcal{X}, y_0 \in \mathcal{Y}, \quad \mathsf{card} \left\{ y \mid \nabla_x c(x_0, y) = \nabla_x c\left(x_0, y_0\right) \right\} \leq m \,. \qquad (\textit{$m$-twist})$$

Suppose that c satisfies (*m*-twist) and is *bounded*. Under the *same assumptions than before*, each optimal plan  $\pi^*$  of ?? is supported on the graphs of  $k \leq m$  measurable maps  $T_i : \mathcal{X} \to \mathcal{Y}$ :

$$\pi^{\star} = \sum_{i=1}^{k} \alpha_i \left( \mathsf{id}, \, T_i \right)_{\#} \mu \,,$$

in the sense  $\pi^*(S) = \sum_{i=1}^k \int_{\mathcal{X}} \alpha_i(x) \mathbb{1}_S(x, T_i(x)) d\mu$  for any Borel  $S \subset \mathcal{X} \times \mathcal{Y}$ .





## Map solutions of OT Recap



• all assumptions needed to apply them are satisfied when  $\mu$  and  $\nu$  have compact support and  $\mu$  has a density

1. Introduction

1.2. Gromov-Wasserstein

# Gromov–Wasserstein [?]

#### Gromov-Wasserstein problem

We consider the following quadratic minimization problem:

$$\inf_{\pi \in \Pi(\mu,\nu)} \iint_{\mathcal{X} \times \mathcal{Y}} |c_{\mathcal{X}}(x,x') - c_{\mathcal{Y}}(y,y')|^{p} d\pi(x,y) d\pi(x',y').$$
(GW)



- quadratic in  $\pi$  +
  - non-convex  $\implies$  much harder than OT
- distance between mm-spaces, *i.e.* GW( $\mathbb{X}, \mathbb{Y}$ ) = 0 iff  $\mathbb{X} = (\mathcal{X}, d_{\mathcal{X}}^{q}, \mu)$  and  $\mathbb{Y} = (\mathcal{Y}, d_{\mathcal{Y}}^{q}, \nu)$  are strongly isomorphic [?]

#### Question

What can be said on the existence of Monge maps for the Gromov–Wasserstein problem?

1. Introduction

1.3. Existing results

#### Context

Let  $n \geq d$ . We consider the GW problem for  $\mu, \nu \in \mathbb{R}^n \times \mathbb{R}^d$  in 2 different settings:

1. the *inner product case*, where  $c_{\mathcal{X}} = c_{\mathcal{Y}} = \langle \cdot, \cdot \rangle$ :

$$\min_{\pi \in \Pi(\mu,\nu)} \iint_{\mathcal{X} \times \mathcal{Y}} |\langle x, x' \rangle - \langle y, y' \rangle|^2 d\pi(x,y) d\pi(x',y'),$$
(GW inner prod)

- e.g. on a d-dimensional sphere  $\mathbb{S}^{d-1}$
- 2. the *quadratic case*, where  $c_{\mathcal{X}} = c_{\mathcal{Y}} = |\cdot|^2$ :

$$\min_{\pi \in \Pi(\mu,\nu)} \iint_{\mathcal{X} \times \mathcal{Y}} \left| |x - x'|^2 - |y - y'|^2 \right|^2 \, \mathrm{d}\pi(x,y) \, \mathrm{d}\pi(x',y') \,,$$
(GW quadratic)

- standard choice for  $c_X$  and  $c_Y$
- $\rightarrow$  both studied in the literature [?, ?]

In the following, n = d.

# Existing results

1. the *inner product case*, where  $c_{\mathcal{X}} = c_{\mathcal{Y}} = \langle \cdot, \cdot \rangle$ :

# [?]

Let  $\mu, \nu \in \mathcal{P}(\mathbb{R}^n)$  of finite second order moment with  $\mu \ll \mathcal{L}^n$ . Suppose that there exists a solution  $\pi^*$  such that  $M^* = \int y \otimes x \, d\pi^*(x, y)$  is of *full rank*. Then there exists an optimal map  $T = \nabla f \circ M^*$  with  $f : \mathbb{R}^n \to \mathbb{R}$  convex.

2. the *quadratic case*, where  $c_{\mathcal{X}} = c_{\mathcal{Y}} = |\cdot|^2$ :

# [?]

Let  $\mu, \nu \in \mathcal{P}(\mathbb{R}^n)$  with *density, rotationally invariant* around their barycenter. Then optimal transport plans are *induced by a map* which is the monotone increasing rearrangement between the radial distributions of  $\mu$  and  $\nu$ .

# [?]

Let  $\mu, \nu \in \mathcal{P}(\mathbb{R}^n)$  with compact support. Assume that  $\mu \ll \mathcal{L}^n$  and that both  $\mu$  and  $\nu$  are centered. *Suppose* that there exists  $\pi^*$  such that  $M^* = \int y \otimes x \, d\pi^*(x, y)$  is of *full rank* and that *there exists a differentiable convex*  $F \colon \mathbb{R} \to \mathbb{R}$  such that  $|T(x)|_2^2 = F'(|x|_2^2)$ , then there exists an optimal map  $T = \nabla f \circ M^*$  with f convex.

Let  $\mu, \nu \in \mathcal{P}(\mathbb{R}^n)$  with compact supports. Suppose  $\mu \ll \mathcal{L}^n$ .

- 1. Theorem: The (GW inner prod) problem admits a *map* as a solution.
- Theorem: The (GW quadratic) problem either admits a *map*, a *bimap* or a *map/anti-map* as a solution.
- 3. **Conjecture:** The second claim is *tight*: there exists cases where optimal solutions of (GW quadratic) are *not maps*.

Bonus: complementary study of (GW quadratic) in dimension one.

2. Monge maps for GW

# Preliminary: bilinear relaxation

Denote (GW) = min<sub> $\pi$ </sub> F( $\pi$ ,  $\pi$ ), F bilinear.

Possible relaxation: (GW)  $\geq \min_{\pi,\gamma} F(\pi,\gamma)$  with  $\pi,\gamma \in \Pi(\mu,\nu)$ .

#### Tightness

If  $c_{\mathcal{Y}}$  and  $c_{\mathcal{X}}$  are both conditionally positive (or both conditionally negative), then the relaxation of  $GW_2^2$  is tight.

If  $(\pi_{\star}, \gamma_{\star})$  minimizer of relaxation, then  $(\pi_{\star}, \pi_{\star})$  and  $(\gamma_{\star}, \gamma_{\star})$  also.

#### Definition

A function  $c_{\mathcal{X}} : \mathcal{X} \times \mathcal{X} \to \mathbb{R}$  is a conditionally negative kernel if for every  $n \ge 1, x_1, \ldots, x_n \in \mathcal{X}$  and every  $\alpha_1, \ldots, \alpha_n$  such that  $\sum_i \alpha_i = 0$  then  $\sum_{ij} \alpha_i \alpha_j c_{\mathcal{X}}(x_i, x_j)$ .

#### Proof.

Problem is *maximization* of a positive quadratic form + elementary computation.

Examples: inner product cost, quadratic cost.

First-order optimality condition Linearization is an OT problem.

- (GW) = min $_{\pi} F(\pi, \pi)$  with F symmetric bilinear
- $\pi^*$  minimizes (GW)  $\implies$  minimizes  $\pi \mapsto 2F(\pi, \pi^*)$ :

$$\min_{\pi\in\Pi(\mu,\nu)}\int C_{\pi^{\star}}(x,y)\,\mathrm{d}\pi(x,y),\quad\text{ with }C_{\pi^{\star}}(x,y)=\int |c_{\mathcal{X}}(x,x')-c_{\mathcal{Y}}(y,y')|^p\,\mathrm{d}\pi^{\star}$$

I will prove something on *one* of the minimizers of the linearization. Tightness of relaxation implies these are also minimizers of GW.

 twist conditions for our linearized costs? ⇒ not always, need something a bit more general.

# 2. Monge maps for GW

2.1. A key lemma

"Let  $\mu, \nu \in \mathcal{P}(E)$ .



"Let  $\mu, \nu \in \mathcal{P}(E)$ . If we can send  $\mu$  and  $\nu$  in a space B by a function  $\varphi$ ,



## A key lemma Intuition

"Let  $\mu, \nu \in \mathcal{P}(E)$ . If we can send  $\mu$  and  $\nu$  in a space B by a function  $\varphi$ , *s.t.*  $c(x, y) = \tilde{c}(\varphi(x), \varphi(y)) \quad \text{for all } x, y \in E$ 

with  $\tilde{c}$  a *twisted* cost on B,



## A key lemma Intuition

"Let  $\mu, \nu \in \mathcal{P}(E)$ . If we can send  $\mu$  and  $\nu$  in a space B by a function  $\varphi$ , s.t.

$$c(x,y) = \tilde{c}(\varphi(x),\varphi(y))$$
 for all  $x,y \in E$ 

with  $\tilde{c}$  a *twisted* cost on *B*, then we can construct an optimal map between  $\mu$ and  $\nu$ ."



### A key lemma Statement

#### Theorem: existence of a Monge map, inner product cost

Let  $E_0$  be a measurable space and  $B_0$  and F be complete Riemannian manifolds. Let  $\mu, \nu \in \mathcal{P}(E_0)$  with *compact support*. Assume that there exists a set  $E \subset E_0$  s.t.  $\mu(E) = 1$  and that there exists a measurable map  $\Phi : E \to B_0 \times F$  that is injective and whose inverse on its image is measurable as well. Let  $\varphi \triangleq p_B \circ \Phi : E \to B_0$ . Let  $c : E_0 \times E_0 \to \mathbb{R}$  and suppose that there exists a *twisted*  $\tilde{c} : B_0 \times B_0 \to \mathbb{R}$  s.t.

## $c(x,y) = \tilde{c}(\varphi(x),\varphi(y))$ for all $x,y \in E_0$ .

Assume that  $\varphi_{\#}\mu \ll \mathcal{L}_{B_0}$  and let thus  $t_B$  denote the unique Monge map between  $\varphi_{\#}\mu$  and  $\varphi_{\#}\nu$  for this cost. Suppose that there exists a disintegration  $((\Phi_{\#}\mu)_u)_u$  of  $\Phi_{\#}\mu$  by  $p_B$  s.t. for  $\varphi_{\#}\mu$ -a.e. u,  $(\Phi_{\#}\mu)_u \ll \text{vol}_F$ .

Then *there exists an optimal map* T between  $\mu$  and  $\nu$  for the cost c that can be decomposed as

$$\Phi \circ \mathcal{T} \circ \Phi^{-1}(u, v) = (t_B(u), t_F(u, v)) = \left(\underbrace{\tilde{c} - \exp_u(\nabla f(u))}_{\in B}, \underbrace{\exp_v(\nabla g_u(v))}_{\in \text{ fiber}}\right),$$

with  $f: B_0 \to \mathbb{R}$   $\tilde{c}$ -convex and  $g_u: F \to \mathbb{R}$   $d_F^2/2$ -convex for  $\varphi_{\#}\mu$ -a.e. u.



- 1. transport in B: c satisfies (Twist) on B;
- 2. *transport the fibers:* choose a map for each couple of fibers  $(\mu_u, \nu_{t_B(u)})$
- is T(u,x) = T<sub>u</sub>(x) measurable? need theorem! adaptation of [?] to the manifold setting

**Take-home message:**  $c(x, y) = \tilde{c}(\varphi(x), \varphi(y))$  with  $\tilde{c}$  twisted  $\implies$  map

# 2. Monge maps for GW

2.2. Application: inner product cost

Let's work on (GW inner prod):

$$\min_{\pi \in \Pi(\mu,\nu)} \iint \left| \langle x, x' \rangle - \langle y, y' \rangle \right|^2 d\pi(x,y) d\pi(x',y') \quad (GW \text{ inner prod})$$

$$\iff \min_{\pi \in \Pi(\mu,\nu)} \iint - \langle x, x' \rangle \langle y, y' \rangle d\pi(x,y) d\pi(x',y')$$

 $\implies \text{OT problem with}$   $c(x, y) = -\int \langle x, x' \rangle \langle y, y' \rangle \, \mathrm{d}\pi^*(x', y') = \cdots = -\langle M^*x, y \rangle$ 

where 
$$M^* \triangleq \int y' x'^\top d\pi^*(x', y') \in \mathbb{R}^{n \times n}$$

rk <i>M*</i>	= <i>n</i>	$\leq n-1$
twist	$\checkmark$	•
subtwist	$\checkmark$	
<i>m</i> -twist, $m \ge 2$	$\checkmark$	

### Inner product cost Proof

1. *a simplification:* up to SVD, suppose  $M^*$  is a diagonal matrix of singular values:

$$M^{\star} = \begin{pmatrix} \sigma_1 & & \\ & \sigma_h & \\ & & 0 \\ & & & 0 \end{pmatrix}$$

2. rephrase the cost:

$$\begin{split} c(x,y) &= -\langle M^* x, y \rangle \\ &= -\sum_{i=1}^h \sigma_i x_i y_i \\ &\triangleq \tilde{c}(p(x), p(y)) \quad \text{ with } p \text{ the orthogonal projection on } \mathbb{R}^h. \end{split}$$

- 3. apply key lemma!
  - B is  $\mathbb{R}^h$
  - fibers are  $\mathbb{R}^{n-h}$
  - $\widetilde{c}$  is twisted on  $\mathbb{R}^h$
- $\Rightarrow$  optimal map + structure!

for 
$$x = (u, v) \in \mathbb{R}^h \times \mathbb{R}^{n-h}$$
,  $T(u, v) = (\nabla f \circ M^*(u), \nabla g_u(v))$ .

# 2. Monge maps for GW

2.3. Application: quadratic cost

Similarly, we work on (GW quadratic) and relax to a classical OT problem with

$$c(x,y) = -|x|^2|y|^2 - 4\langle M^*x, y\rangle.$$

rk <i>M</i> *	= n	= n - 1	$\leq n-2$
twist	•		•
subtwist	$\checkmark$		
2-twist	$\checkmark$	$\checkmark$	•

Similarly, we work on (GW quadratic) and relax to a classical OT problem with

$$c(x,y) = -|x|^2|y|^2 - 4\langle M^*x, y\rangle.$$

rk <i>M*</i>	= n	= n - 1	$\leq n-2$
twist	•		
subtwist	$\checkmark$		
2-twist	$\checkmark$	$\checkmark$	
	$\downarrow$	$\Downarrow$	$\downarrow$
	map/anti-map and bimap	bimap	

#### Theorem: quadratic cost

Let  $\mu, \nu \in \mathcal{P}(\mathbb{R}^n)$  of compact support. Suppose that  $\mu$  has a density. Let  $\pi^*$  be an optimal plan and  $M^* \triangleq \int y' x'^\top d\pi^*(x', y')$ . Then:

- $\checkmark$  if rk  $M^* = n$ , there is an optimal *map/anti-map*,
- $\checkmark$  if rk  $M^* = n 1$ , there is an optimal *bimap*,

(!!) if  $rk M^* \leq n - 2$ , there is an optimal map!

1. a simplification: up to SVD,  $M^*$  is diagonal:

$$M^{\star} = \begin{pmatrix} \sigma_1 & & \\ & \sigma_h & \\ & & 0 \end{pmatrix}. \quad \text{We note } x = (\underbrace{x_1, \dots, x_h}_{x_H}, \underbrace{x_{h+1}, \dots, x_n}_{x_{\perp}}).$$

2. rephrase the cost:

$$\begin{aligned} -c(x,y) &= |x|^2 |y|^2 + 4 \langle M^* x, y \rangle \\ &= |x_H|^2 |y_H|^2 + |x_H|^2 |y_\perp|^2 + |x_\perp|^2 |y_H|^2 + |x_\perp|^2 |y_\perp|^2 + 4 \langle \tilde{M} x_H, y_H \rangle \\ &= |x_H|^2 |y_H|^2 + |x_H|^2 n(y) + n(x) |y_H|^2 + n(x) n(y) + 4 \langle \tilde{M} x_H, y_H \rangle \\ &\triangleq -\tilde{c}(\varphi(x), \varphi(y)), \end{aligned}$$

with  $n: x \mapsto |x_{\perp}|^2$  and  $\varphi: x \mapsto (x_H, |x_{\perp}|^2)$ .

- 3. apply key lemma!
  - B is  $\mathbb{R}^h \times \mathbb{R}^+$
  - the fibers are spheres  $\mathbb{S}^{n-h-1}$
  - $\tilde{c}$  is twisted on  $\mathbb{R}^h\times\mathbb{R}^+$
- $\Rightarrow$  optimal map + structure!

for  $x \approx (u, v) \in \mathbb{R}^h \times \mathbb{R}^h \times \mathbb{S}^{n-h-1}$ ,  $T(u, v) = (\tilde{c} - \exp_u(\nabla f(u)), \exp_v(\nabla g_u(v)))$ .

3. Summary & discussion

## Summary & discussion

#### Contributions

- 1. Thm: always a *map* for (GW inner prod)
- 2. **Thm:** a *map*, *bimap* or *map/anti-map* for (GW quadratic)
- 3. Numerical Conj: this second claim is tight
- 4. (**Thm:** monotone rearrangement optimal for (GW quadratic) between measures composed of *two distant parts*): global dominates the local.

#### Some questions:

- quadratic cost:
  - better understanding of the 1d case.
- A (motivated) cost with tractable GW and structured maps?